

# Sea Level Measurement Device Design Competition Workshop on "Circuit Design and Its Applications"

## 海平面量度裝置設計比賽 「電路設計及應用」工作坊

Department of Electrical & Electronic Engineering

The University of Hong Kong

香港大學 電機電子工程系

Thomas Kwan / Andy Fok (CB103)

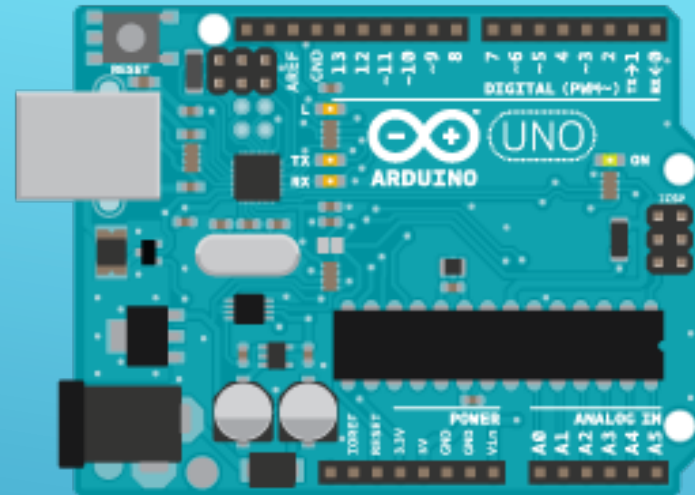
Garfield Lam / Simon Tam (CB-LG205)

# What is Arduino? Arduino 是甚麼？

Arduino is an Open-Source Electronics Platform based on easy-to-use hardware and software.

It's intended for anyone making interactive projects.

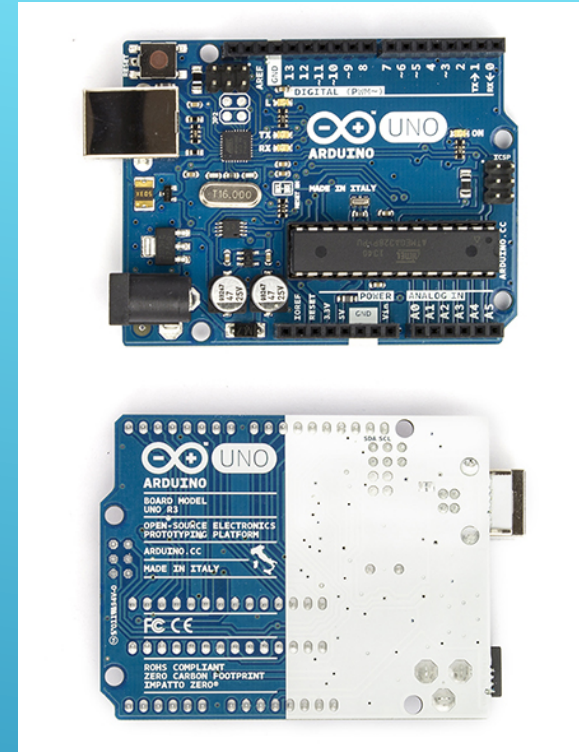
Arduino 是開源易用，包含軟硬件的電子平台，給所有人設計互動的電子項目。



Name	Processor	Operating Voltage/Input Voltage	CPU Speed	Analog In/Out	Digital IO/PWM	EEPROM [KB]	SRAM [KB]	Flash [KB]	USB	UART
<b>Uno</b>	ATmega328	5 V/7-12 V	16MHz	6/0	14/6	1	2	32	Regular	1
<b>Due</b>	AT91SAM3X8E	3.3 V/7-12 V	84 MHz	12/2	54/12	-	96	512	2 Micro	4
<b>Leonardo</b>	ATmega32u4	5 V/7-12 V	16MHz	12/0	20/7	1	2.5	32	Micro	1
<b>Mega 2560</b>	ATmega2560	5 V/7-12 V	16MHz	16/0	54/15	4	8	256	Regular	4
<b>Mega ADK</b>	ATmega2560	5 V/7-12 V	16MHz	16/0	54/15	4	8	256	Regular	4
<b>Micro</b>	ATmega32u4	5 V/7-12 V	16MHz	12/0	20/7	1	2.5	32	Micro	1
<b>Mini</b>	ATmega328	5 V/7-9 V	16MHz	8/0	14/6	1	2	32	-	-
<b>Nano</b>	ATmega168 ATmega328	5 V/7-9 V	16MHz	8/0	14/6	0.512 1	1 2	16 32	Mini-B	1
<b>Ethernet</b>	ATmega328	5 V/7-12 V	16MHz	6/0	14/4	1	2	32	Regular	-
<b>Esplora</b>	ATmega32u4	5 V/7-12 V	16MHz	-	-	1	2.5	32	Micro	-
<b>ArduinoBT</b>	ATmega328	5 V/2.5-12 V	16MHz	6/0	14/6	1	2	32	-	1
<b>Fio</b>	ATmega328P	3.3 V/3.7-7 V	8MHz	8/0	14/6	1	2	32	Mini	1
<b>Pro (168)</b>	ATmega168	3.3 V/3.35-12 V	8MHz	6/0	14/6	0.512	1	16	-	1
<b>Pro (328)</b>	ATmega328	5 V/5-12 V	16MHz	6/0	14/6	1	2	32	-	1
<b>Pro Mini</b>	ATmega168	3.3 V/3.35-12 V 5 V/5-12 V	8MHz 16MHz	6/0	14/6	0.512	1	16	-	1
<b>LilyPad</b>	ATmega168V ATmega328V	2.7-5.5 V/2.7-5.5 V	8MHz	6/0	14/6	0.512	1	16	-	-
<b>LilyPad USB</b>	ATmega32u4	3.3 V/3.8-5V	8MHz	4/0	9/4	1	2.5	32	Micro	-
<b>LilyPad Simple</b>	ATmega328	2.7-5.5 V/2.7-5.5 V	8MHz	4/0	9/4	1	2	32	-	-
<b>LilyPad SimpleSnap</b>	ATmega328	2.7-5.5 V/2.7-5.5 V	8MHz	4/0	9/4	1	2	32	-	-
<b>Yun</b>	ATmega32u4	5 V	16MHz	12/0	20/7	1	2.5	32	Micro	1

# Arduino UNO

Microcontroller 微控制器	ATmega328
Operating Voltage 工作電壓	5V
Input Voltage (recommended) 輸入電壓 (建議值)	7-12V
Input Voltage (limits) 輸入電壓 (範圍)	6-20V
Digital I/O Pins 數碼輸入輸出端	14 (of which 6 provide PWM output) 14 (6 可作 PWM 輸出)
Analog Input Pins 模擬輸入端	6
DC Current per I/O Pin 每輸入輸出端之直流電流	40 mA
DC Current for 3.3V Pin 3.3V 端之直流電流	50 mA
Flash Memory Flash 記憶	32 KB (ATmega328), of which 0.5 KB used by bootloader 32 KB (ATmega328), 其中0.5KB予bootloader用
SRAM	2 KB (ATmega328)
EEPROM	1 KB (ATmega328)
Clock Speed 時鐘頻率	16 MHz



```
void setup() {  
  }  
  
void loop() {  
  }
```

## Arduino Software Arduino 軟件

You can tell your Arduino what to do by writing code in the Arduino programming language and using the Arduino development environment.

你可以利用Arduino的開發環境，寫程式告訴Arduino做些甚麼。

### Arduino IDE 1.0.6

- [Windows Installer](#), [Windows ZIP file \(for non-administrator install\)](#)
- [Mac OS X](#)
- [Linux: 32 bit, 64 bit](#)
- [source](#)

# Getting Started with Arduino on Windows

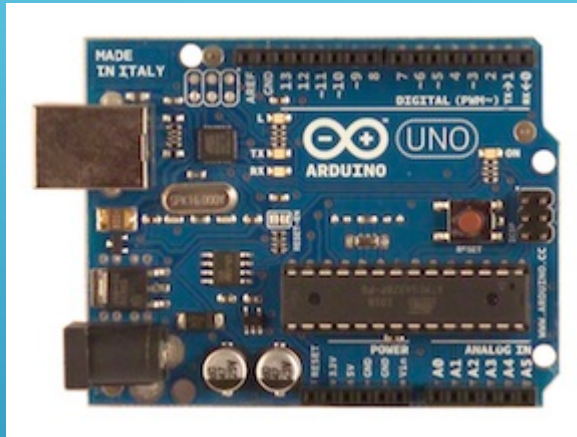
## Arduino 在 Windows 入門

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- 1 | Get an Arduino board and USB cable 取得 Arduino 模板及 USB 線
- 2 | Download the Arduino environment 下載 Arduino 環境
- 3 | Connect the board 接上 Arduino 板
- 4 | Install the drivers 安裝驅動程式
- 5 | Launch the Arduino application 啟動 Arduino 應用程式
- 6 | Open the blink example 打開範例程式 blink
- 7 | Select your board 選取所用的 Arduino 板
- 8 | Select your serial port 選擇所所用的串流連接埠
- 9 | Upload the program 上傳程式

# 1 | Get an Arduino UNO board and USB cable

取得 Arduino 模板及 USB 線



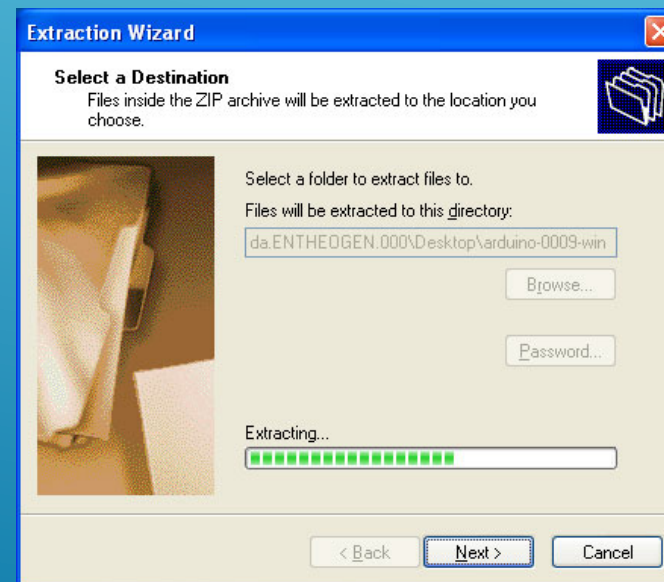
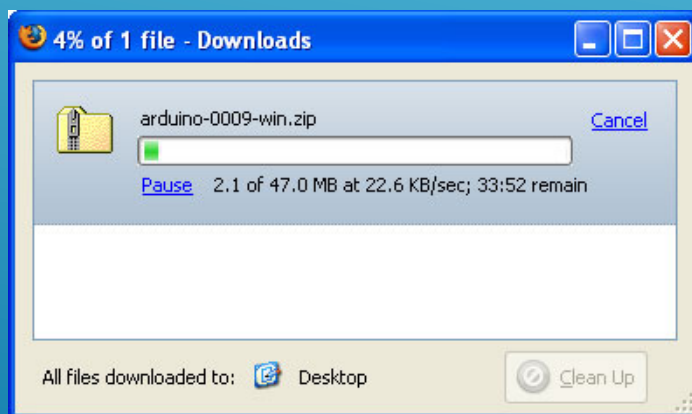
## 2 | Download the Arduino environment 下載 Arduino 環境

Get the latest version from the [download page](#).

When the download finishes, unzip the downloaded file. Make sure to preserve the folder structure. Double-click the folder to open it. There should be a few files and sub-folders inside.

從下載頁下載最新的 Arduino 環境。

下載後，unzip 下載了的檔案。不要改動文件夾結構。打開文件夾，內裏應有一些文件和子文件夾。





### 3 | Connect the board 接上 Arduino 板

The Arduino automatically draw power from either the USB connection to the computer or an external power supply.

Connect the Arduino board to your computer using the USB cable. The green power LED (labelled **PWR**) should go on.

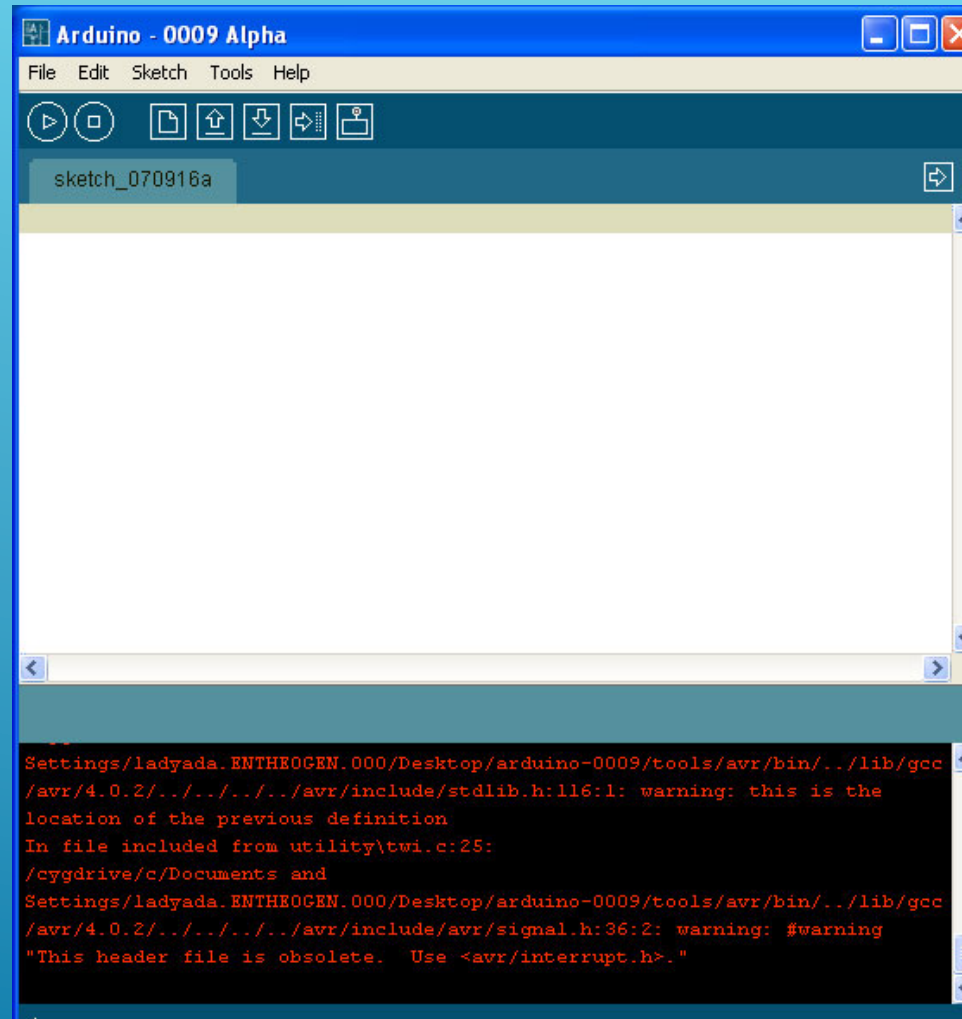
Arduino 可從 USB 取得電源，亦可利用外部電源。  
利用 USB 線將 Arduino 板連接至電腦。你應見到一粒在旁印有“PWR”的綠色的發光二極管（LED）亮着。



## 4 | Install the drivers 安裝驅動程式

- Plug in your board and wait for Windows to begin its driver installation process. After a few moments, the process will fail, despite its best efforts.  
連接 Arduino 板至電腦。Windows 會尋找驅動程式，然後失敗。
- Click on the Start Menu, and open up the Control Panel. 按開始，打開控制台。
- While in the Control Panel, navigate to System and Security. Next, click on System. Once the System window is up, open the Device Manager. 控制台內，打開「系統」，開「裝置管理員」。
- Look under Ports (COM & LPT). You should see an open port named "Arduino UNO (COMxx)". If there is no COM & LPT section, look under "Other Devices" for "Unknown Device".  
打開「連接埠 (COM和LPT)」。如沒有，則打開「其他裝置」。
- Right click on the "Arduino UNO (COMxx)" port and choose the "Update Driver Software" option.  
右擊「Arduino UNO (COMxx)」，選「更新驅動程式軟體」。
- Next, choose the "Browse my computer for Driver software" option.  
選「手動尋找並安裝驅動程式軟體」。
- Finally, navigate to and select the driver file named "**arduino.inf**", located in the "Drivers" folder of the Arduino Software download (not the "FTDI USB Drivers" sub-directory). If you are using an old version of the IDE (1.0.3 or older), choose the Uno driver file named "**Arduino UNO.inf**".  
選在「Drivers」文件夾內的「arduino.inf」文件（注意：不是「FTDI USB Drivers」文件夾）。如你用舊版 Arduino IDE（1.0.3 版或以前），則選「Arduino UNO.inf」。
- Windows will finish up the driver installation from there. 驅動程式會自動完成。

## 5 | Launch the Arduino application 啟動 Arduino 應用程式



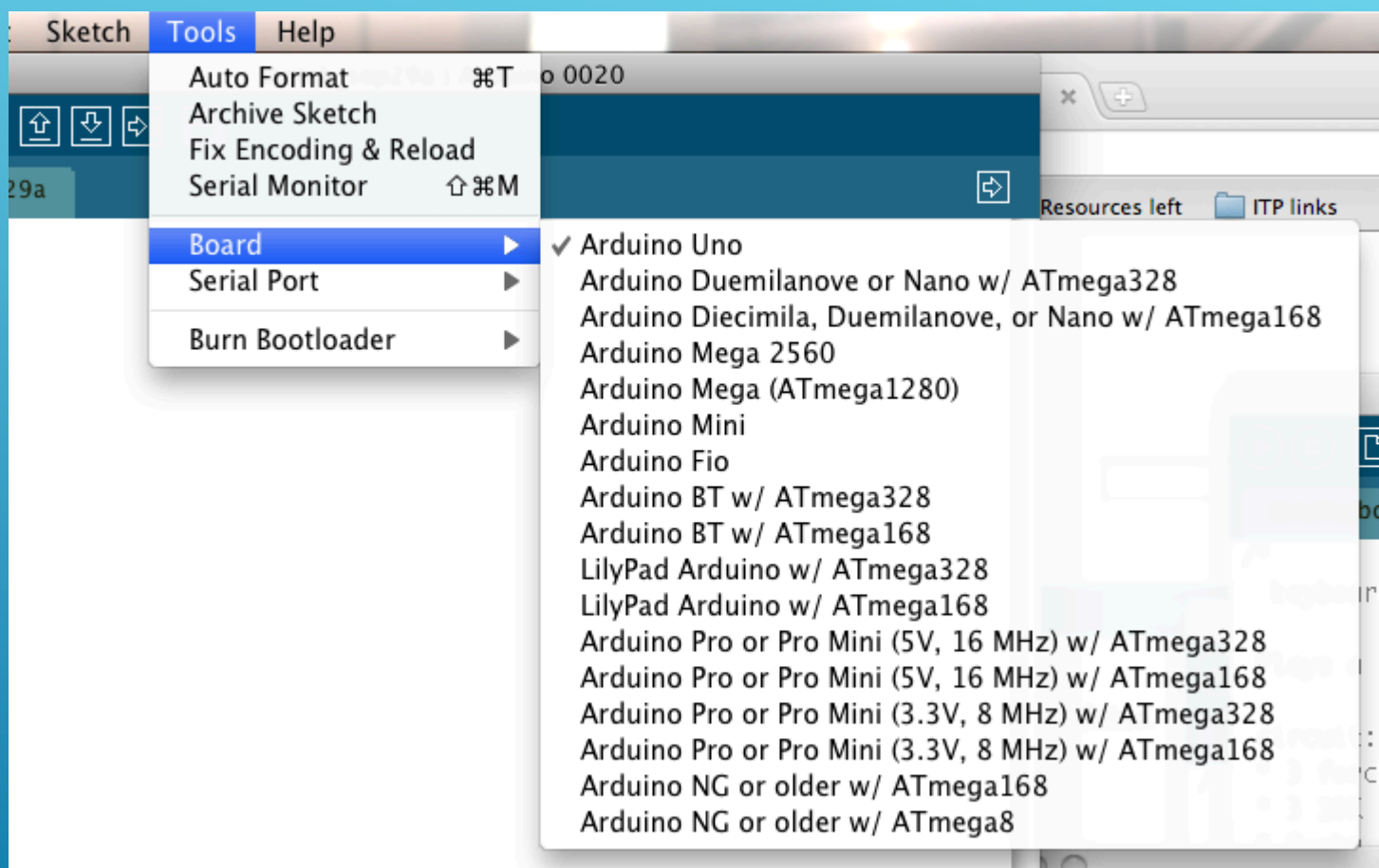
## 6 | Open the blink example 打開範例程式 blink

A screenshot of the Arduino IDE interface. The window title is "Blink | Arduino 1.0". The top toolbar contains icons for a checkmark, a right arrow, a document, an upload arrow, a download arrow, and a search icon. Below the toolbar is a tab labeled "Blink". The main text area contains the following code:

```
/*  
  Blink  
  Turns on an LED on for one second, then off for one second, repeatedly.  
  
  This example code is in the public domain.  
  */  
  
void setup() {  
  // initialize the digital pin as an output.  
  // Pin 13 has an LED connected on most Arduino boards:  
  pinMode(13, OUTPUT);  
}  
  
void loop() {  
  digitalWrite(13, HIGH); // set the LED on  
  delay(1000);           // wait for a second  
  digitalWrite(13, LOW); // set the LED off  
  delay(1000);           // wait for a second  
}
```

The bottom status bar shows "1" on the left and "Arduino Uno on /dev/tty.usbmodemfd131" on the right.

## 7 | Select your board 選取所用的 Arduino 板



## 8 | Select your serial port 選擇所所用的串流接口

Select the serial device of the Arduino board from the Tools | Serial Port menu. This is likely to be **COM3** or higher (**COM1** and **COM2** are usually reserved for hardware serial ports). To find out, you can disconnect your Arduino board and re-open the menu; the entry that disappears should be the Arduino board. Reconnect the board and select that serial port.

從 Tools > Serial Port menu 選所用的串流連接埠。通常會是 COM3 或以上，因為 COM1 和 COM2 通常留作內部使用。要找出是哪個埠，可以斷開 Arduino 和電腦的連接，關掉重開 Tools > Serial Port 頁，消失了的 COM 埠，就是所用的那個。重接 Arduino 板後便可選取。

## 9 | Upload the program 上載程式

Click the “Upload” button in the environment 點擊 Upload 鍵。



After the upload finishes, you should see the pin 13 (L) LED on the board start to blink (in orange).

上載完成後，接到第 13 腳的發光二極管（橙色）會開始閃動。

## Basic Command Description 基本程式碼的說明

`pinMode(n, INPUT)` Set pin *n* to act as an input. One-time command at top of program.  
將第 *n* 腳作為輸入端。只需程式開始時進行一次。

`pinMode(n, OUTPUT)` Set pin *n* to act as an output 將第 *n* 腳作為輸出端。

`digitalWrite(n, HIGH)` Set pin *n* to 5V 將第 *n* 腳輸出成 5 伏特。

`digitalWrite(n, LOW)` Set pin *n* to 0V 將第 *n* 腳輸出成 0 伏特。

`delay(x)` Pause program for *x* milliseconds, *x* = 0 to 65535. 程式等待 *x* 毫秒。 *x* 由 0 至 65535。

`for() {}` For loop. 迴圈敘述。

Example 例: `for(i=0;i<3;i++) {}`

Do the instructions enclosed by {} three times. 將 {} 內的指令做 3 次。

`if (expr) {}` Conditional branch. 條件式敘述。

If *expr* true, do instructions enclosed by {} 如 *expr* 條件式成立，執行 {} 內的指令。

`while (expr) {}` While loop. While 迴圈敘述。

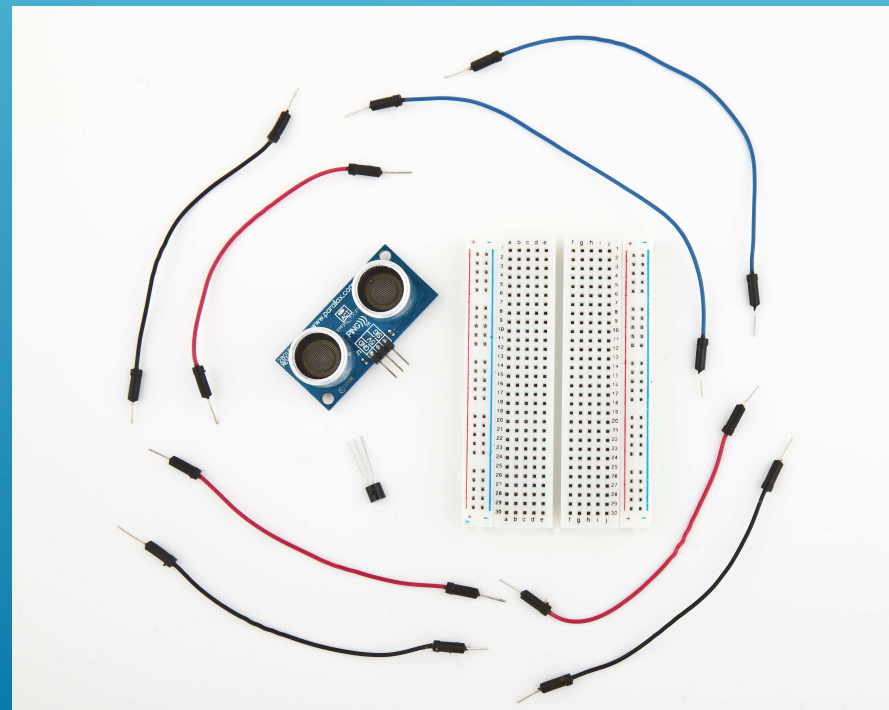
While *expr* is true, repeat instructions in {} indefinitely

當 *expr* 條件式成立，執行 {} 內的指令，直至 *expr* 條件式不成立。

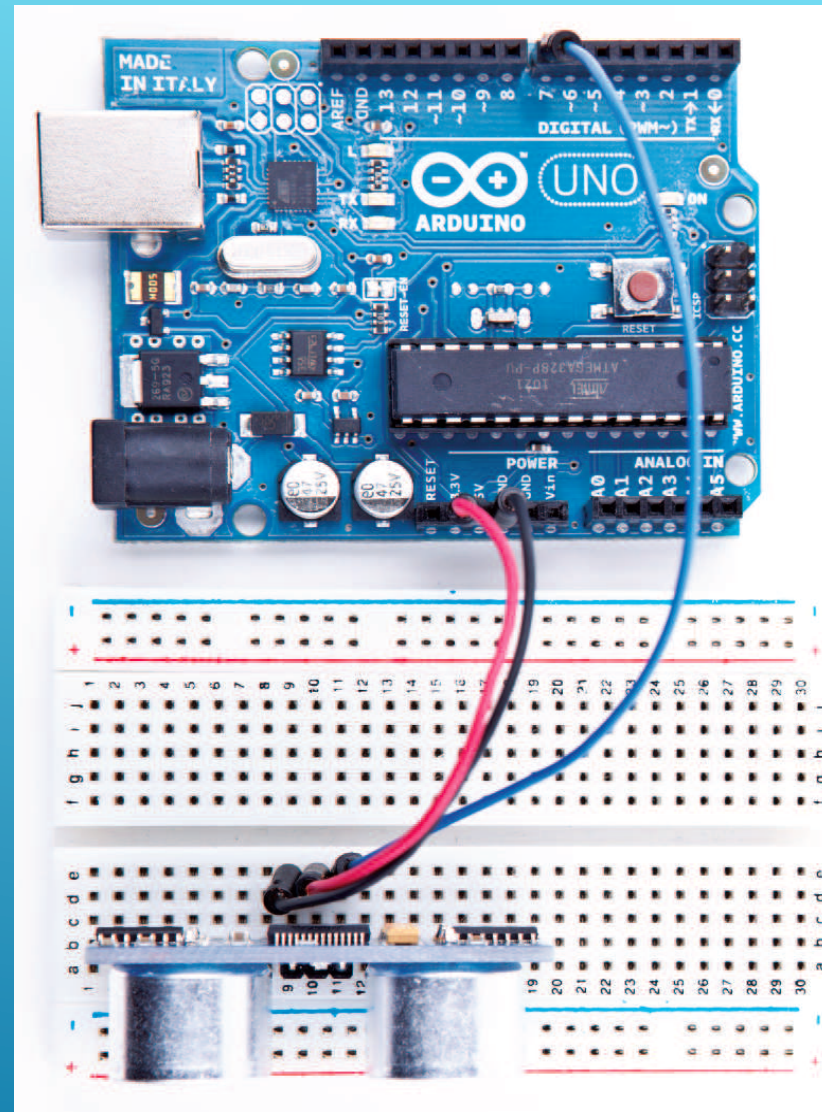
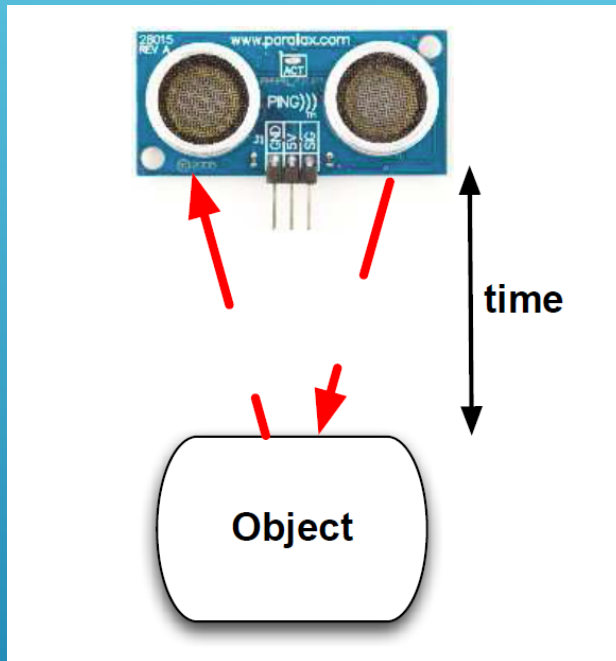


Parallax PING))) sensor  
Parallax PING))) 傳感器

<http://www.parallax.com/product/28015>



Parallax PING))) sensor  
Parallax PING))) 傳感器



# Parallax PING))) sensor Parallax PING))) 傳感器

```
const unsigned int PING_SENSOR_IO_PIN = 7;  
const unsigned int BAUD_RATE = 9600;
```

```
void setup() {  
  Serial.begin(BAUD_RATE);  
}
```

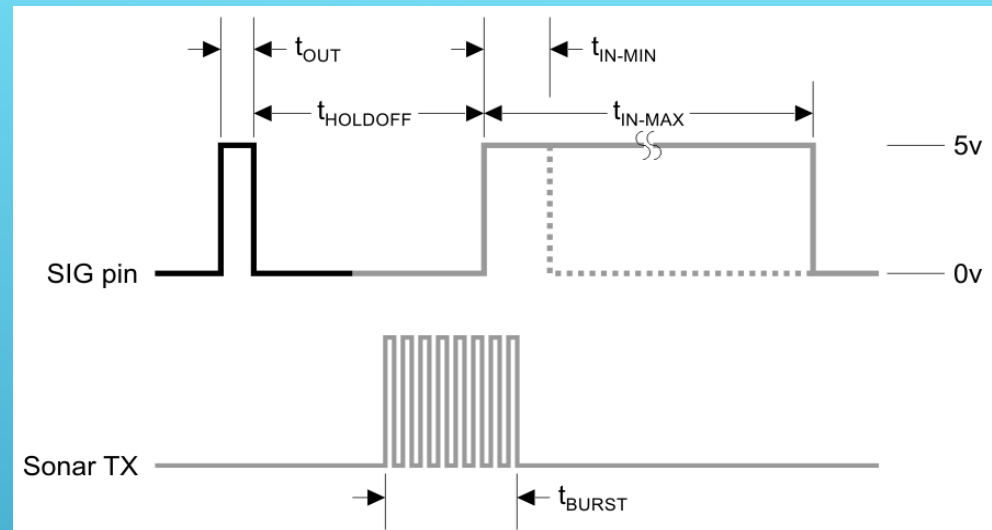
```
void loop() {  
  pinMode(PING_SENSOR_IO_PIN, OUTPUT);  
  digitalWrite(PING_SENSOR_IO_PIN, LOW);  
  delayMicroseconds(2);
```

```
  digitalWrite(PING_SENSOR_IO_PIN, HIGH);  
  delayMicroseconds(5);  
  digitalWrite(PING_SENSOR_IO_PIN, LOW);
```

```
  pinMode(PING_SENSOR_IO_PIN, INPUT);  
  const unsigned long duration = pulseIn(PING_SENSOR_IO_PIN, HIGH);  
  if (duration == 0) {  
    Serial.println("Warning: We did not get a pulse from sensor.");  
  } else {  
    Serial.print("Distance to nearest object: ");  
    Serial.print(microseconds_to_cm(duration));  
    Serial.println(" cm");  
  }  
}
```

```
  delay(100);  
}
```

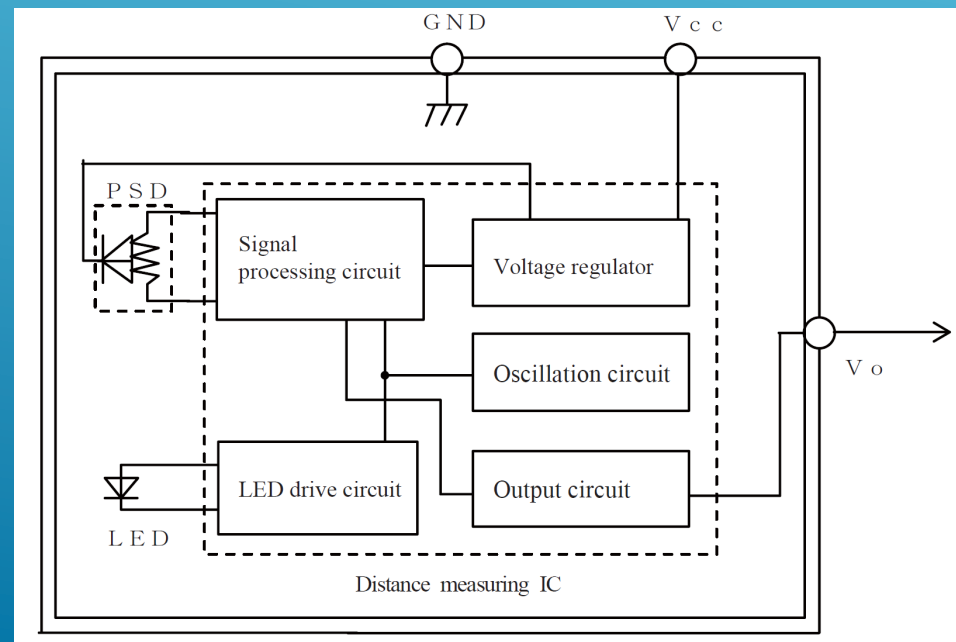
```
unsigned long microseconds_to_cm(const unsigned long microseconds) {  
  return microseconds / 29 / 2;  
}
```



## Sharp Distance Measuring Sensor

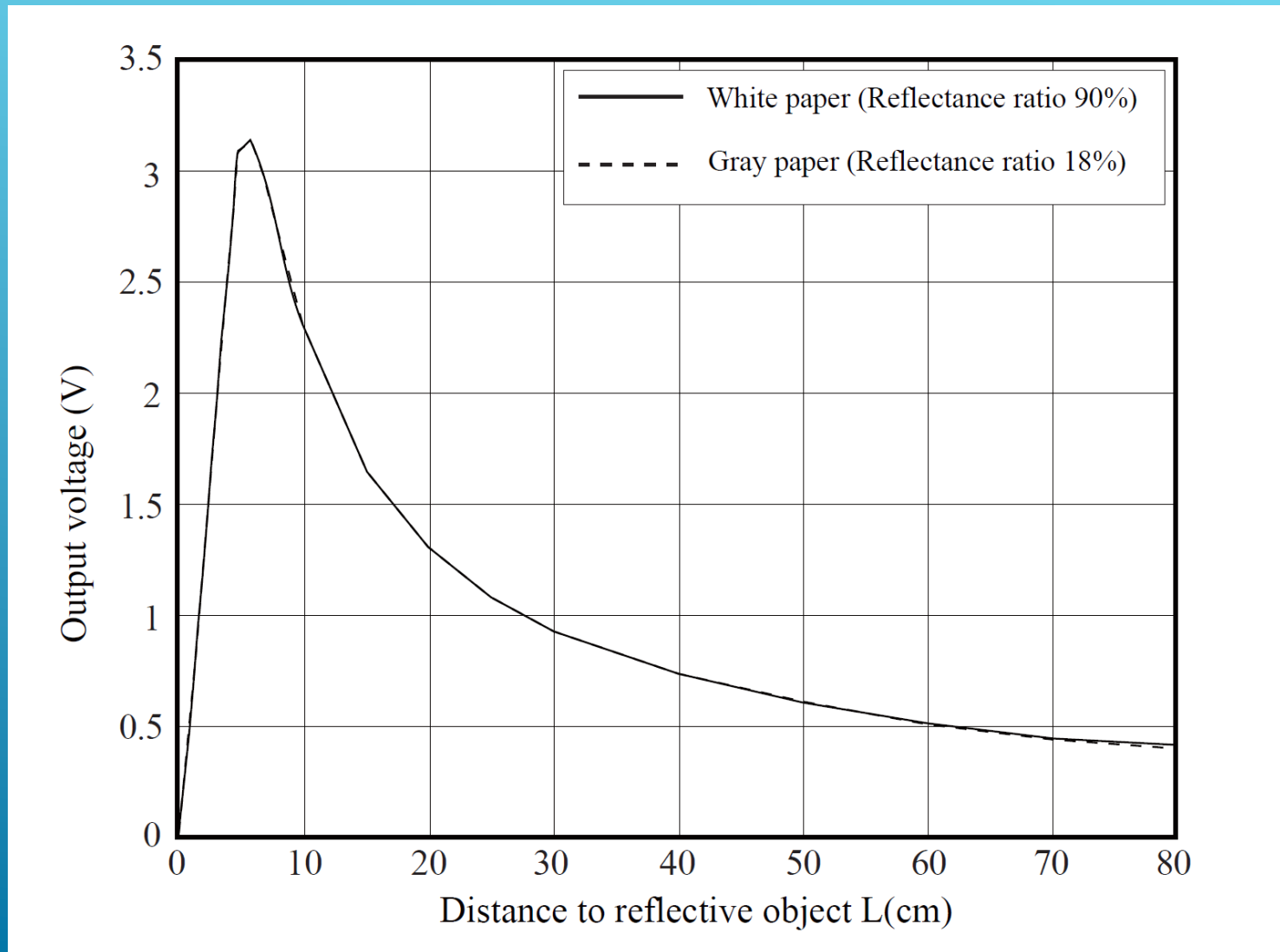
### Sharp 測距傳感器

- Distance measurement range: 10 to 80 cm (3.9 to 31.5 inches)  
量度距離：10 至 80 厘米（3.9 至 31.5 吋）
- Analog output voltage corresponds to distance.  
模擬輸出電壓和距離相關。
- Operates on 4.5-5.5 V supply.  
電源 4.5 至 5.5 伏特。



# Sharp Distance Measuring Sensor

## Sharp 測距傳感器

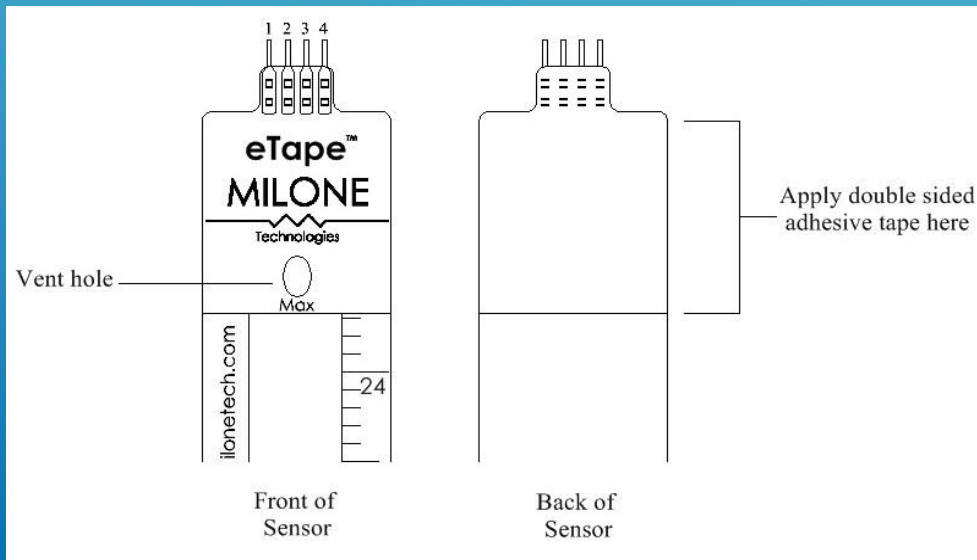


# Parallax eTape Standard Liquid Level Sensor (12-inch) #29131

## Parallax eTape 標準液位傳感器 (12吋) #29131

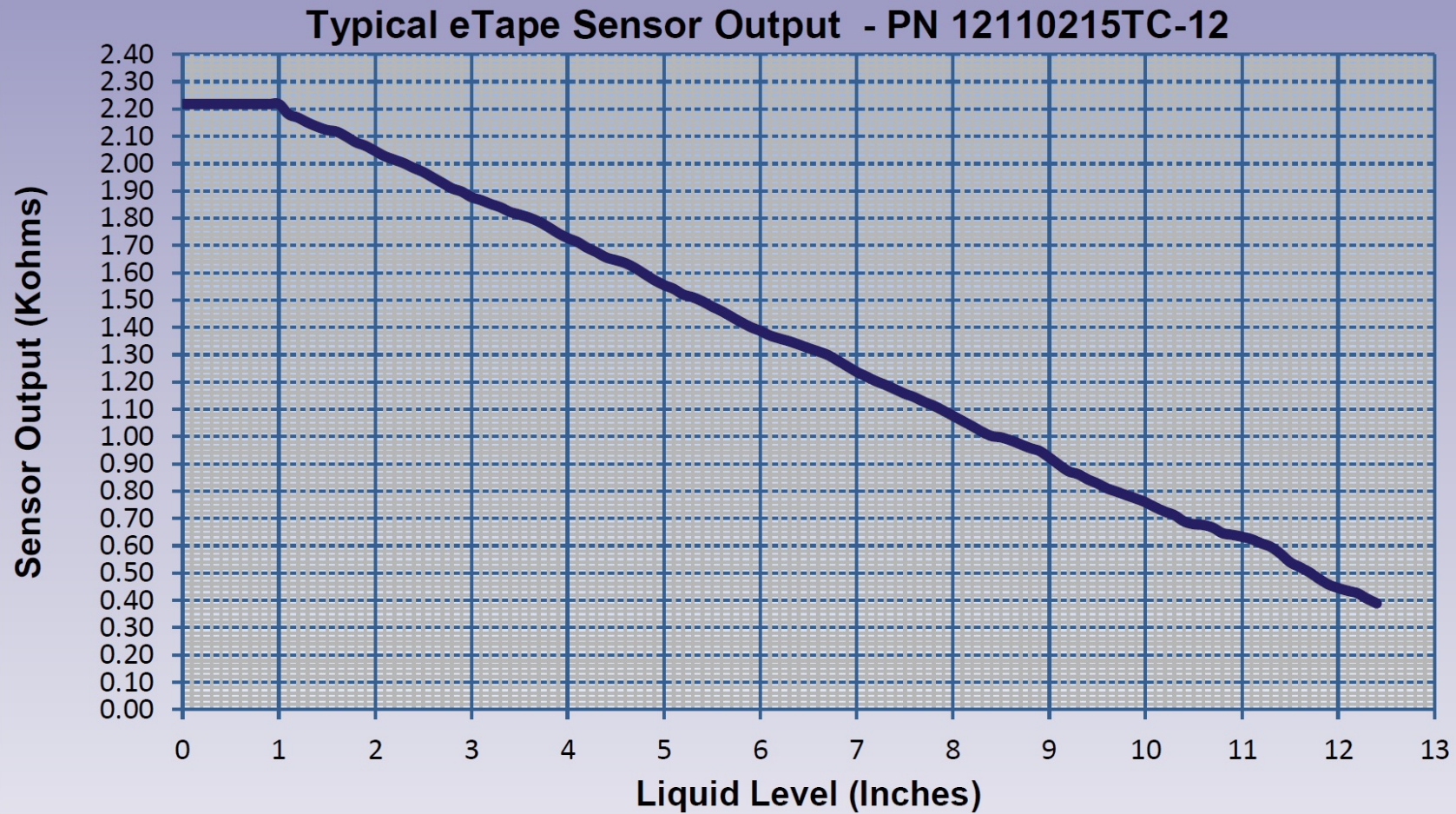


<http://www.parallax.com/product/29131>



Parallax eTape Standard Liquid Level Sensor (12-inch) #29131

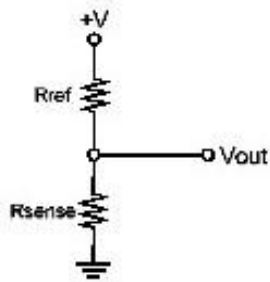
Parallax eTape 標準液位傳感器 (12吋) #29131



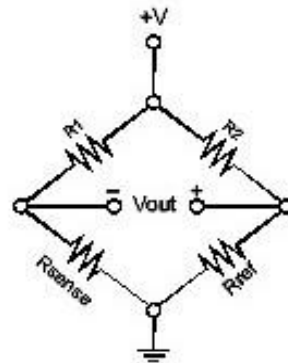
# Parallax eTape Standard Liquid Level Sensor (12-inch) #29131

## Parallax eTape 標準液位傳感器 (12吋) #29131

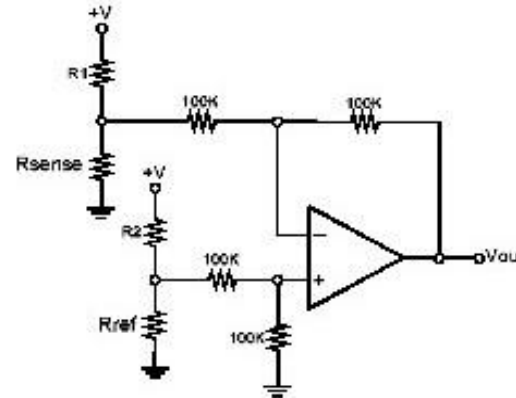
Simple Voltage Divider



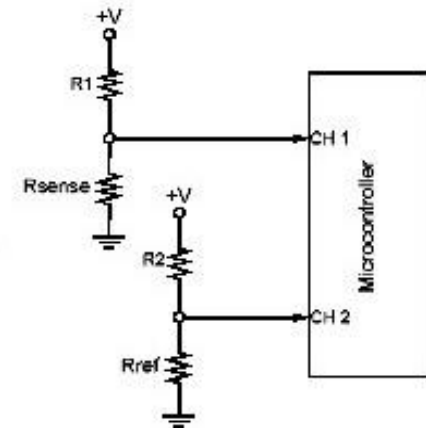
Wheatstone Bridge



Differential Op-Amp



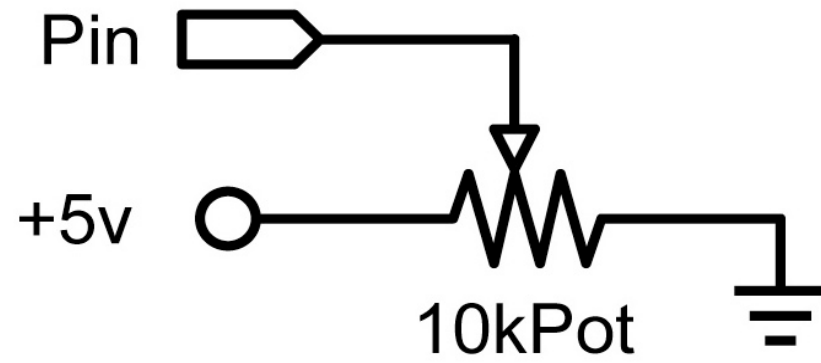
Voltage Dividers and Microcontroller



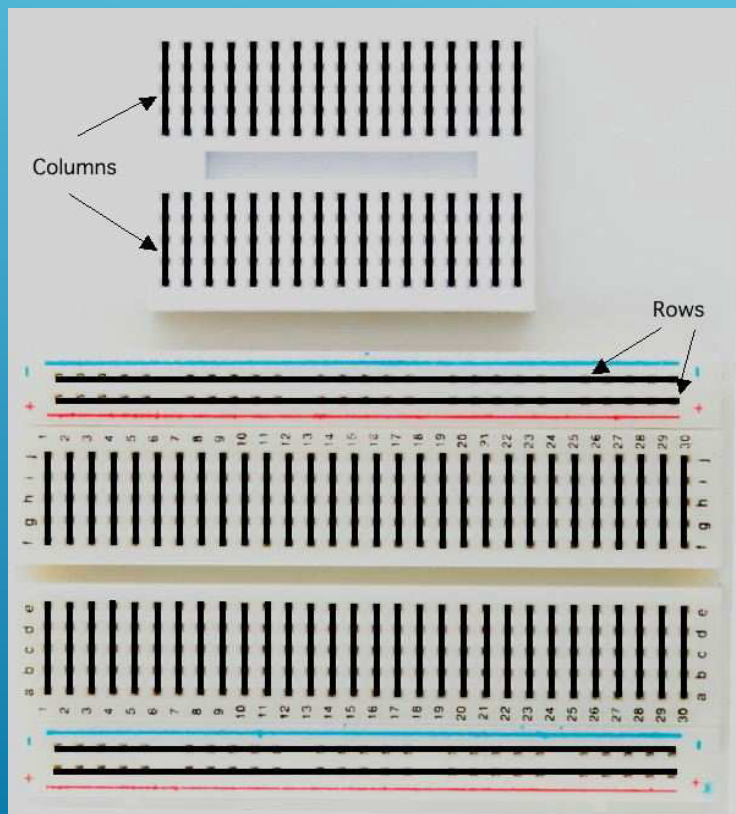


## Potentiometer Input

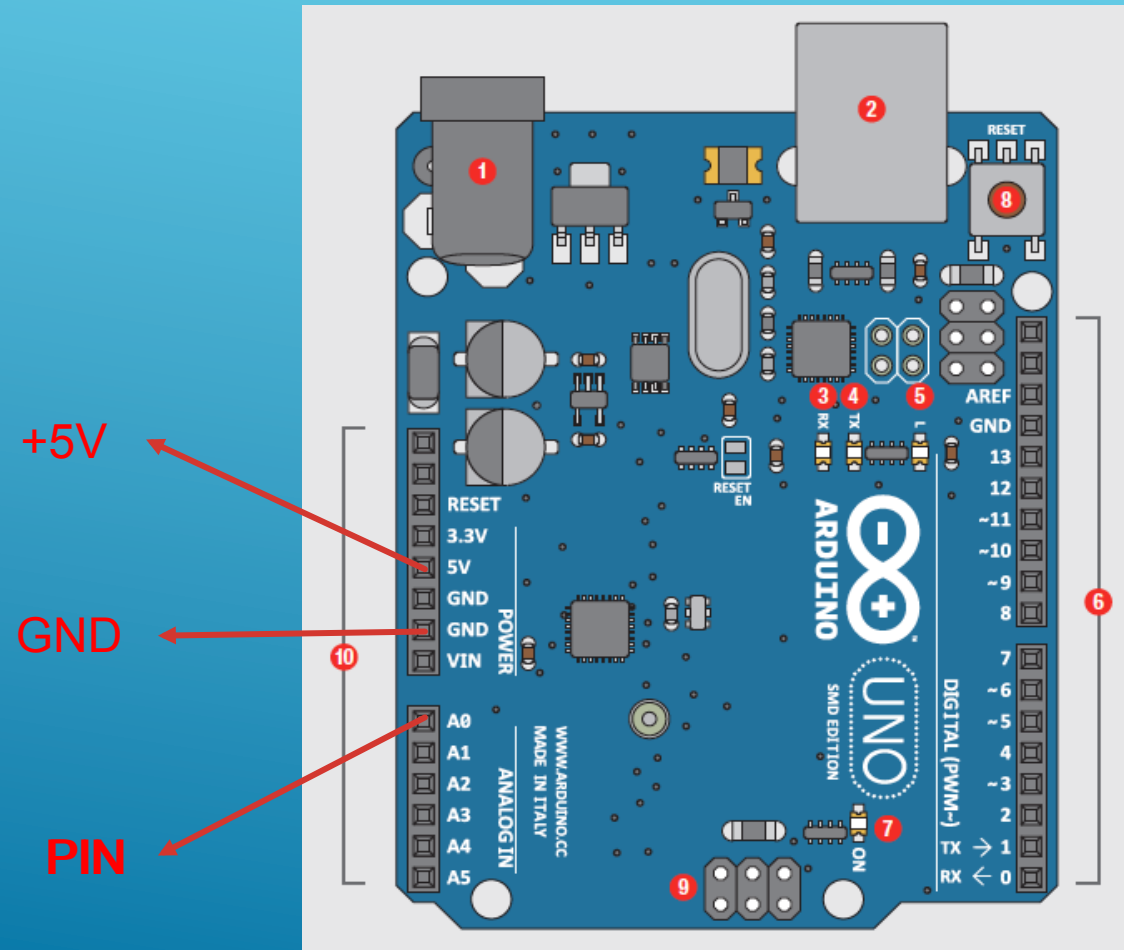
電位器輸入



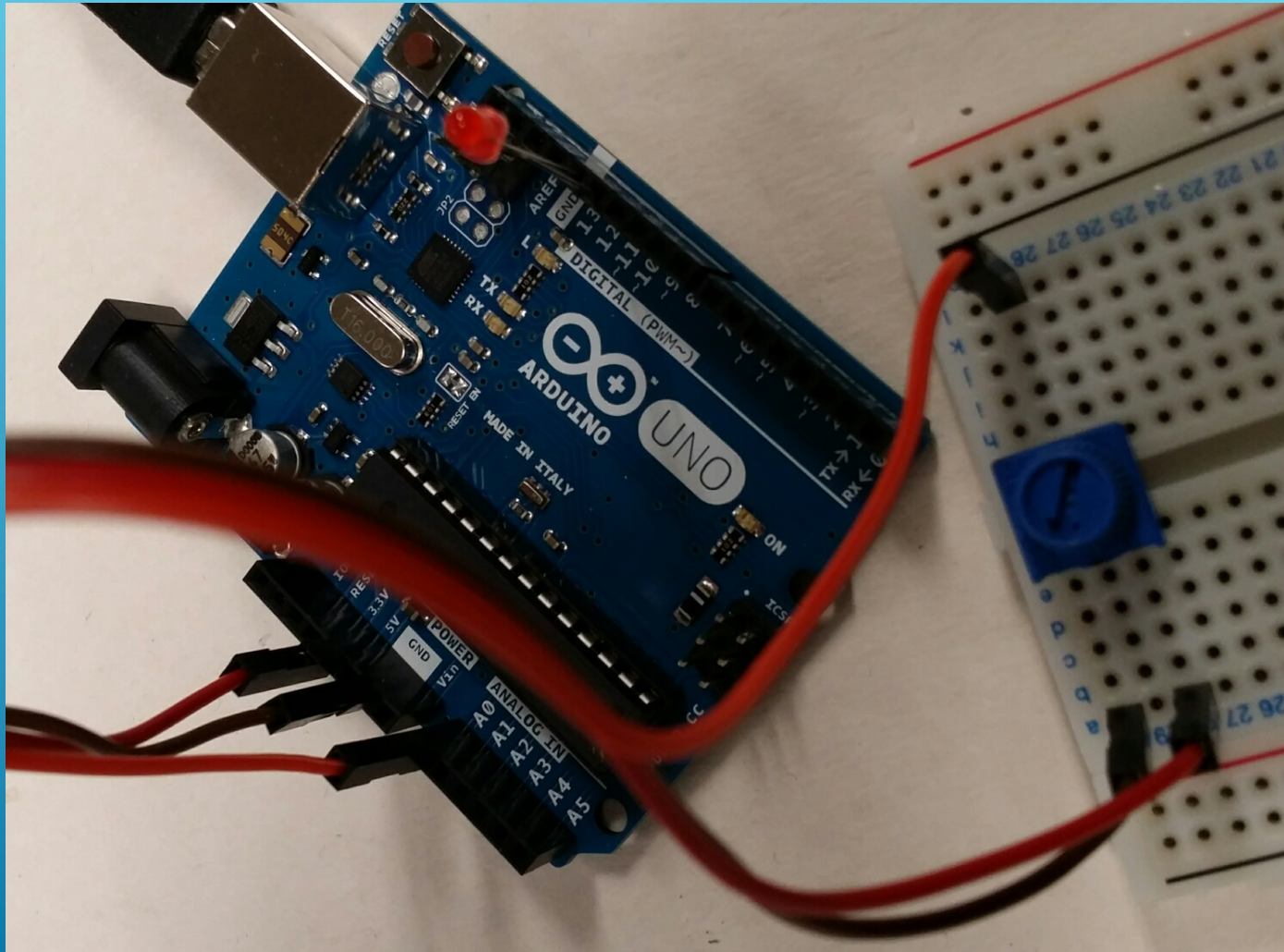
# Bread Board 麵包板



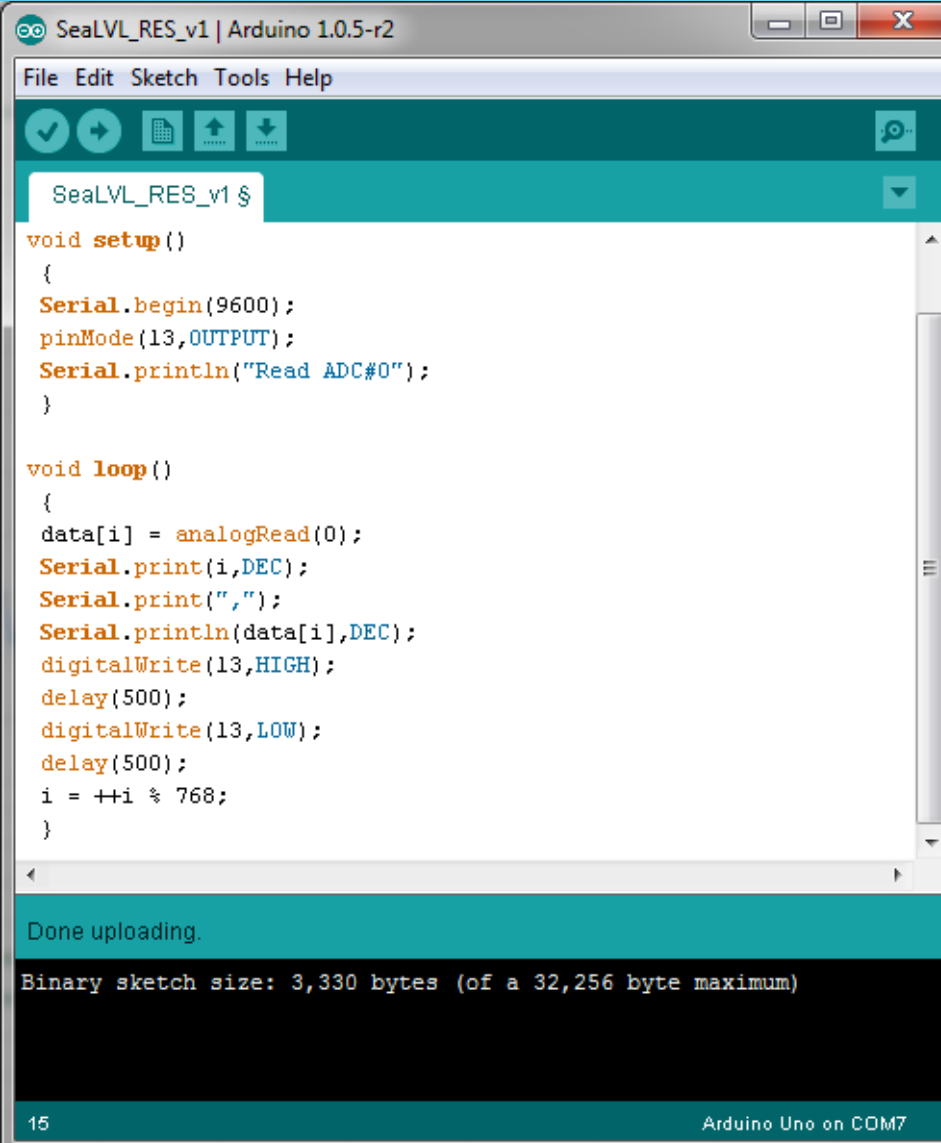
# Circuit connection 電路連接



## Circuit connection 電路連接



## Programming 程式



The screenshot shows the Arduino IDE interface. The title bar reads "SealVL\_RES\_v1 | Arduino 1.0.5-r2". The menu bar includes "File", "Edit", "Sketch", "Tools", and "Help". The toolbar contains icons for saving, running, uploading, and downloading. The main editor area shows the following code:

```
SealVL_RES_v1 $
void setup()
{
  Serial.begin(9600);
  pinMode(13,OUTPUT);
  Serial.println("Read ADC#0");
}

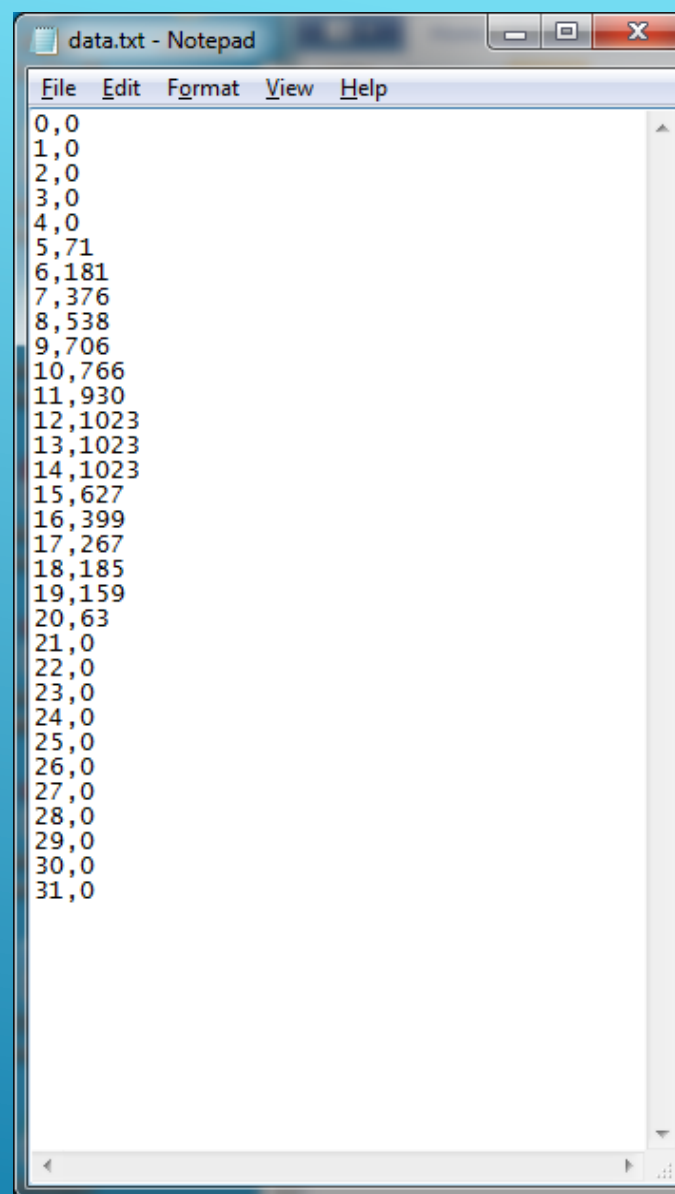
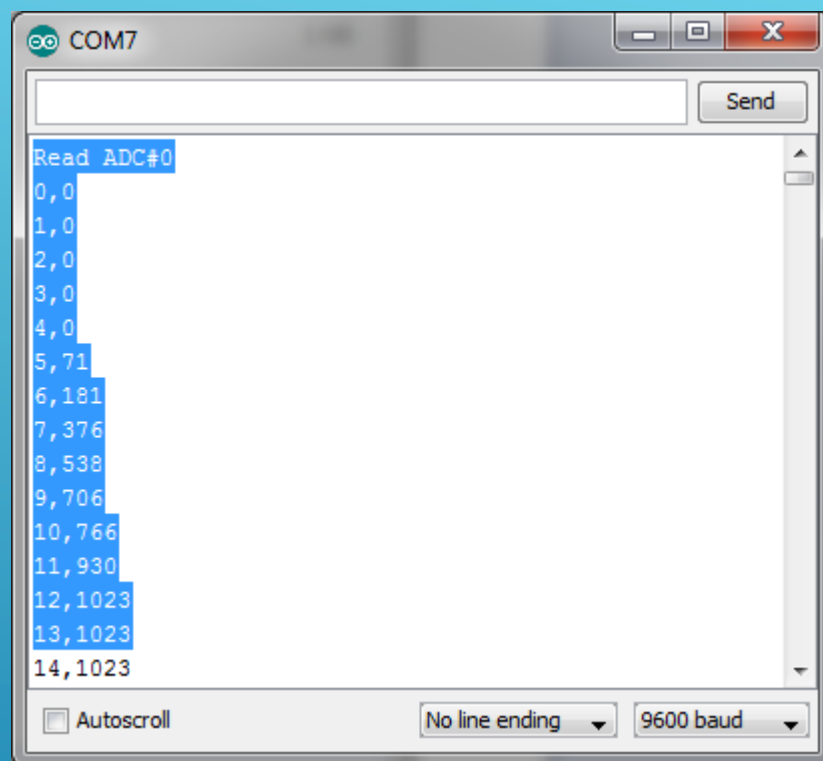
void loop()
{
  data[i] = analogRead(0);
  Serial.print(i,DEC);
  Serial.print(",");
  Serial.println(data[i],DEC);
  digitalWrite(13,HIGH);
  delay(500);
  digitalWrite(13,LOW);
  delay(500);
  i = ++i % 768;
}
```

Below the editor is a console window with the following output:

```
Done uploading.
Binary sketch size: 3,330 bytes (of a 32,256 byte maximum)
```

The status bar at the bottom indicates "15" on the left and "Arduino Uno on COM7" on the right.

## Data Logging 記錄資料



# Graph Plotting 繪製圖表

